

Braid index of spatial graphs

Ken Kanno

0 Spatial Graph

In this paper we work in piecewise linear category. Let G be a finite graph, and \mathbb{R}^3 be an 3-dimensional Euclidean space. A *spatial embedding* of G is an embedding $g : G \rightarrow \mathbb{R}^3$ of G , and its image is called a *spatial graph*. A graph G is *planar* if there exists an embedding $G \rightarrow \mathbb{R}^2$. A *diagram* is a regular projection of spatial graph that has relative height information added to it at each of the double points.

1 Reidemeister moves for Spatial Graphs

Theorem 1.1 *Two spatial embeddings f and g is ambient isotopic if there exists an orientation preserving homeomorphism Φ such that $\Phi \circ f = g$.*

Kauffman has defined *Reidemeister moves for graphs*[1], which consist of traditional Reidemeister moves for links and extra two moves involving a vertex.

Theorem 1.2 *If two spatial graphs are ambient isotopic then any two diagrams of them are related by a finite sequence of Reidemeister moves for graphs.*

2 Braid index for θ_n -curve

Let G be a θ_n -curve in \mathbb{R}^3 , such that all edges are oriented so that the origin and terminus of each edges are the same. We can obtain a *braid presentation* of θ_n -curve in the way that we obtained a link by a closure of a braid[2].

Theorem 2.1 *Any θ_n -curve has a braid presentation.*

We intend to expand this braid presentation for simply oriented θ_n -curve to an arbitrarily oriented θ_n -curve and other spatial graphs.

References

- [1] L.Kauffman, *Invariants of graphs in three-space*, Trans. Amer. Math. Soc., **311**(1989), 697-710.
- [2] T.Shinnoki, and T.Takamuki, *On the braid index of θ_m -curve in 3-space*, Math. Nachr., **260**(2003), 84-92.